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with $x(t_0)=x_0$, has a unique solution over $[t_0,t_1]$ The global Lipschitz condition is satisfied for linear systems of the form $\dot{x} = A(t)x+g(t)$ but it is a restrictive condition for general nonlinear systems
NonlinearControlLecture#1Introduction

NonlinearControl Lecture#1 Introduction

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Problem 1 – Behavior of a non-linear system Study the behavior of the system $\dot{x} = y$ (1a) $\dot{y} = -2x - 2y - 4x^2$ (1b) with regard to its initial value and assess if the system is globally asymptotically stable. We have chosen a solution strategy based on the Figure 1.1: The homework report title page.

EL2620 Nonlinear Control Exercises and Homework

This section provides materials for a session on a special type of 2x2 nonlinear systems called autonomous systems. Materials include course notes, a lecture video clip, JavaScript Mathlets, and a problem set with solutions.

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